|  |  |  |  |
| --- | --- | --- | --- |
| **Name** | Jenny Reiman | Jason Laqua | Andrew Kirkham |
| **Hours** | 4 | 5 | 6 |
| **Reading** | <http://www.vexrobotics.com/276-2174.html> | <http://en.wikipedia.org/wiki/Rotary_encoder>  <https://www.cresis.ku.edu/~cgifford/eecs690/Vex_Robotics_Tutorial.pdf> | <http://stackoverflow.com/questions/14986146/update-android-ui-from-a-thread-in-another-class>  <https://developers.google.com/maps/documentation/android/start>  <https://developers.google.com/maps/documentation/android/map> |
| **Tasks Completed** | Other sensor  Cliff test | Interrupts  Redesign robot | Android UI  Communication Android to vex |
| **Tasks for Thursday** | Optical Sensor | Testing Straightness | Android UI |

**Open issues:**

|  |  |  |  |
| --- | --- | --- | --- |
| **What** | **Who** | **When** | **Done** |
| Iteration one tasks | All | 9-26 | ✓ |
| Android UI | Andrew | Oct - 3 | ✓ |
| Communication between VEX and Android | All | Oct-10 | ✓ |
| Android can get GPS coordinates | Andrew | Oct-10 |  |
| Robot moves to GPS coordinate | All | Oct-31 |  |
| Robot moves in straight line | Jason | Oct-17 |  |
| Robot uses sensors | Jenny | Oct-30 |  |
| Cliff test | Jenny | Oct-24 | ✓ |